



**Variable frequency drive, 400 V AC, 3-phase, 46 A, 22 kW, IP21/NEMA1, Brake chopper, DC link choke**

**Part no. DG1-34046FB-C21C**  
**Catalog No. 9702-3001-00P**  
**Eaton Catalog No. DG1-34046FB-C21C**  
**EL-Nummer 4138076**  
**(Norway)**

## Delivery program

|                                  |          |    |   |
|----------------------------------|----------|----|---|
| Product range                    |          |    | Variable frequency drives   |
| Part group reference (e.g. DIL)  |          |    | DG1   |
| Rated operational voltage        | $U_e$    |    | 400 V AC, 3-phase<br>480 V AC, 3-phase<br>500 V AC, 3-phase   |
| Output voltage with $V_e$        | $U_2$    |    | 400 V AC, 3-phase<br>480 V AC, 3-phase<br>500 V AC, 3-phase   |
| Mains voltage (50/60Hz)          | $U_{LN}$ | V  | 380 (-15%) - 500 (+10%)   |
| <b>Rated operational current</b> |          |    |   |
| At 150% overload                 | $I_e$    | A  | 46  |
| At 110% overload                 | $I_e$    | A  | 61  |
| Note                             |          |    | Rated operational current for a switching frequency of 1 - 12 kHz and an ambient temperature of +50 °C for a 150% overload and +40 °C for a 110% overload         |
| <b>Assigned motor rating</b>     |          |    |   |
| Note                             |          |    | for normal internally and externally ventilated 4 pole, three-phase asynchronous motors with $1500 \text{ rpm}^{-1}$ at 50 Hz or $1800 \text{ min}^{-1}$ at 60 Hz |
| Note                             |          |    | Overload cycle for 60 s every 600 s   |
| Note                             |          |    | at 400 V, 50 Hz   |
| 150 % Overload                   | P        | kW | 22  |
| 110 % Overload                   | P        | kW | 30  |
| 150 % Overload                   | $I_M$    | A  | 41  |
| 110 % Overload                   | $I_M$    | A  | 55.2  |
| Note                             |          |    | at 500 V, 50 Hz   |
| 150 % Overload                   | P        | kW | 30  |
| 110 % Overload                   | P        | kW | 37  |
| 150 % Overload                   | $I_M$    | A  | 44  |
| 110 % Overload                   | $I_M$    | A  | 54  |
| Note                             |          |    | at 480 V, 60 Hz   |
| 150 % Overload                   | P        | HP | 30  |
| 110 % Overload                   | P        | HP | 40  |
| 150 % Overload                   | $I_M$    | A  | 40  |
| 110 % Overload                   | $I_M$    | A  | 52  |
| Degree of Protection             |          |    | IP21/NEMA1  |
| Interface/field bus (built-in)   |          |    | Modbus RTU<br>Modbus TCP<br>BACnet MS/TP<br>Ethernet IP   |
| Fieldbus connection (optional)   |          |    | PROFIBUS<br>CANopen®<br>DeviceNet<br>SmartWire-DT   |
| Fitted with                      |          |    | Radio interference suppression filter<br>Additional PCB protection<br>Multi-line graphic display<br>Brake chopper<br>DC link choke                                |

|                            |  |  |  |
|----------------------------|--|--|--|
| Frame size                 |  |  | FS3  |
| Connection to SmartWire-DT |  |  | yes<br>in conjunction with DXG-NET-SWD SmartWire DT module |

## Technical data

### General

|                                   |          |    |  |
|-----------------------------------|----------|----|--|
| Standards                         |          |    | Specification for general requirements: IEC/EN 61800-2<br>EMC requirements: IEC/EN 61800-3<br>Safety requirements: IEC/EN 61800-5  |
| Certifications                    |          |    | CE, UL, cUL, c-Tick, UkrSEPRO, EAC   |
| Production quality                |          |    | RoHS, ISO 9001   |
| Climatic proofing                 | $\rho_w$ | %  | < 95%, average relative humidity (RH), non-condensing, non-corrosive   |
| Air quality                       |          |    | 3C2, 3S2   |
| Ambient temperature               |          |    |  |
| operation (150 % overload)        | $\theta$ | °C | -30 - +50 (max. +60 with 1 % derating per Kelvin temperature rise)   |
| operation (110 % overload)        | $\theta$ | °C | -30 - +40 (max. +55 mit 1 % Derating pro Kelvin Temperaturerhöhung)  |
| Storage                           | $\theta$ | °C | -40 - +70  |
| Overvoltage category              |          |    | III  |
| Pollution degree                  |          |    | 2  |
| Radio interference level          |          |    |  |
| Radio interference class (EMC)    |          |    | C1 (with external filter, for conducted emissions only), C2, C3, depending on the motor cable length, the connected load, and ambient conditions. External radio interference suppression filters (optional) may be necessary. |
| Environment (EMC)                 |          |    | 1st and 2nd environments as per EN 61800-3   |
| maximum motor cable length        | l        | m  | C2 ≤ 10 m<br>C3 ≤ 50 m   |
| Mechanical shock resistance       |          | g  | EN 61800-5-1, EN 60068-2-27<br>UPS drop test (for weights inside the UPS frame)<br>Storage and transportation: maximum 15 g, 11 ms (inside the packaging)  |
| Vibration                         |          |    | EN 61800-5-1, EN 60068-2-6: 5 - 150 Hz<br>Amplitude: 1 mm (peak) at 5 - 15.8 Hz<br>Maximum acceleration amplitude: 1 g at 15.8 – 150 Hz  |
| Mounting position                 |          |    | Vertical   |
| Altitude                          |          | m  | 0 - 1000 m above sea level<br>Above 1000 m: 1% derating for every 100 m<br>max. 3000 m (2000 m for Corner Grounded TN Systems)   |
| Degree of Protection              |          |    | IP21/NEMA1   |
| Protection against direct contact |          |    | BGV A3 (VBG4, finger- and back-of-hand proof)  |

### Main circuit

|   |          |    |   |
|---|----------|----|---|
| Supply                                  |          |    |   |
| Rated operational voltage               | $U_e$    |    | 400 V AC, 3-phase<br>480 V AC, 3-phase<br>500 V AC, 3-phase                     |
| Mains voltage (50/60Hz)                 | $U_{LN}$ | V  | 380 (-15%) - 500 (+10%)   |
| Input current (150% overload)           | $I_{LN}$ | A  | 42.6  |
| Input current (110% overload)           | $I_{LN}$ | T  | 55.7  |
| System configuration                    |          |    | TN-S, TN-C, TN-C-S, TT, IT  |
| Supply frequency                        | $f_{LN}$ | Hz | 50/60   |
| Frequency range                         | $f_{LN}$ | Hz | 45 - 66   |
| Mains switch-on frequency               |          |    | Maximum of one time every 60 seconds  |
| Mains current distortion                | THD      | %  | 32.6  |
| Rated conditional short-circuit current | $I_q$    | kA | < 100   |
| Power section                           |          |    |   |
| Function                                |          |    | Variable frequency drive with internal DC link, DC link choke and IGBT inverter |
| Overload current (150% overload)        | $I_L$    | A  | 69  |
| Overload current (110% overload)        | $I_L$    | A  | 67.1  |
| max. starting current (High Overload)   | $I_H$    | %  | 200   |
| Note about max. starting current        |          |    | for 2 seconds every 20 seconds  |
| Output voltage with $V_e$               | $U_2$    |    | 400 V AC, 3-phase<br>480 V AC, 3-phase<br>500 V AC, 3-phase                     |

|   |            |          |   |
|---|------------|----------|---|
| Output Frequency  | $f_2$      | Hz       | 0 - 50/60 (max. 400)  |
| Switching frequency   | $f_{PWM}$  | kHz      | 4<br>adjustable 1 - 12  |
| Operation Mode  |            |          | U/f control<br>Speed control with slip compensation<br>sensorless vector control (SLV)<br>Torque regulation   |
| Frequency resolution (setpoint value)                       | $\Delta f$ | Hz       | 0.01  |
| Rated operational current                                   |            |          |   |
| At 150% overload  | $I_e$      | A        | 46  |
| At 110% overload  | $I_e$      | A        | 61  |
| Note  |            |          | Rated operational current for a switching frequency of 1 - 12 kHz and an ambient temperature of +50 °C for a 150% overload and +40 °C for a 110% overload         |
| Motor current limit   | $I$        | A        | $0.1 - 2 \times I_H$ (CT)   |
| Power loss  |            |          |   |
| Heat dissipation at rated operational current $I_e = 150\%$ | $P_V$      | W        | 541   |
| Heat dissipation at rated operational current $I_e = 110\%$ | $P_V$      | W        | 818   |
| Efficiency  | $\eta$     | %        | 97.7  |
| Maximum leakage current to ground (PE) without motor        | $I_{PE}$   | mA       | 12.2  |
| Fan   |            |          | temperature controlled<br>Tool-less swapping  |
| Internal fan delivery rate                                  |            | $m^3/h$  | 144   |
| Fitted with   |            |          | Radio interference suppression filter<br>Additional PCB protection<br>Multi-line graphic display<br>Brake chopper<br>DC link choke                                |
| Safety function   |            |          | STO (Safe Torque Off, SIL1, PLc Cat 1)  |
| Frame size  |            |          | FS3   |
| Motor feeder  |            |          |   |
| Note  |            |          | for normal internally and externally ventilated 4 pole, three-phase asynchronous motors with $1500 \text{ rpm}^{-1}$ at 50 Hz or $1800 \text{ min}^{-1}$ at 60 Hz |
| Note  |            |          | Overload cycle for 60 s every 600 s   |
| Note  |            |          | at 400 V, 50 Hz   |
| 150 % Overload  | P          | kW       | 22  |
| 110 % Overload  | P          | kW       | 30  |
| Note  |            |          | at 500 V, 50 Hz   |
| 150 % Overload  | P          | kW       | 30  |
| 110 % Overload  | P          | kW       | 37  |
| Note  |            |          | at 480 V, 60 Hz   |
| 150 % Overload  | P          | HP       | 30  |
| 110 % Overload  | P          | HP       | 40  |
| maximum permissible cable length                            | $l$        | m        | screened: 150   |
| Apparent power  |            |          |   |
| Apparent power at rated operation 400 V                     | S          | kVA      | 42.3  |
| Apparent power at rated operation 480 V                     | S          | kVA      | 52.8  |
| Braking function  |            |          |   |
| Standard braking torque                                     |            |          | max. 30 % $M_N$   |
| DC braking torque   |            |          | adjustable to 150 %   |
| Braking torque with external braking resistance             |            |          | Max. 100% of rated operational current $I_e$ with external braking resistor   |
| minimum external braking resistance                         | $R_{min}$  | $\Omega$ | 14  |
| Switch-on threshold for the braking transistor              | $U_{DC}$   | V        | 850 V DC  |
| DC braking  | %          | $I/I_e$  | $\leq 150$ , adjustable   |
| <b>Control section</b>                                      |            |          |   |
| External control voltage                                    | $U_c$      | V        | 24 V DC (max. 250 mA options incl.)   |
| Reference voltage   | $U_s$      | V        | 10 V DC (max. 10 mA)  |
| Analog inputs   |            |          | 2, parameterizable, 0 - 10 V DC, 2 - 10 V DC, -10 - +10 V DC, 0/4 - 20 mA   |
| Analog outputs  |            |          | 2, parameterizable, 0 - 10 V, 0/4 - 20 mA   |
| Digital inputs  |            |          | 8, parameterizable, max. 30 V DC  |

|                                |  |  |   |
|--------------------------------|--|--|---|
| Digital outputs                |  |  | 1, parameterizable, 24 V DC   |
| Relay outputs                  |  |  | 3, parameterizable, 2 changeover contacts and 1 N/O, 6 A (240 VAC) / 6 A (24 VDC) |
| Interface/field bus (built-in) |  |  | Modbus RTU<br>Modbus TCP<br>BACnet MS/TP<br>Ethernet IP                           |
| Expansion slots                |  |  | 2   |

### Assigned switching and protective elements

|   |  |   |  |
|---|--|---|--|
| Power Wiring  |  |   |  |
| Safety device (fuse or miniature circuit-breaker)                             |  |   |  |
| IEC (Type B, gG), 150 %   |  |   | PKZM4-50   |
| IEC (Type B, gG), 110 %   |  |   | PKZM4-63   |
| UL (Class CC or J)  |  | A | 80   |
| Mains contactor   |  |   |  |
| 150 % overload (CT/I <sub>H</sub> , at 50 °C)                                 |  |   | DILM40   |
| 110 % overload (VT/I <sub>L</sub> , at 40 °C)                                 |  |   | DILM50   |
| Main choke  |  |   |  |
| 150 % overload (CT/I <sub>H</sub> , at 50 °C)                                 |  |   | Integrated DC link choke, uk = 5%  |
| 110 % overload (VT/I <sub>L</sub> , at 40 °C)                                 |  |   | Integrated DC link choke, uk = 5%  |
| Radio interference suppression filter (external, 150 %)                       |  |   | DX-EMC34-055   |
| Radio interference suppression filter (external, 110 %)                       |  |   | DX-EMC34-075   |
| Radio interference suppression filter, low leakage currents (external, 150 %) |  |   | DX-EMC34-055-L   |
| Radio interference suppression filter, low leakage currents (external, 110 %) |  |   | DX-EMC34-075-L   |
| Note regarding radio interference suppression filter                          |  |   | Optional external radio interference suppression filter for longer motor cable lengths and for use in different EMC environments |
| DC link connection  |  |   |  |
| Braking resistance  |  |   |  |
| 10 % duty factor (DF)   |  |   | P:3 x DX-BR047-3K1   |
| 20 % duty factor (DF)   |  |   | P:3 x DX-BR047-5K1   |
| 40 % duty factor (DF)   |  |   | P:3 x DX-BR047-9K2   |
| Notes concerning braking resistances:   |  |   | P:n = "n" resistors connected in parallel  |
| Motor feeder  |  |   |  |
| motor choke   |  |   |  |
| 150 % overload (CT/I <sub>H</sub> , at 50 °C)                                 |  |   | DX-LM3-050   |
| 110 % overload (VT/I <sub>L</sub> , at 40 °C)                                 |  |   | DX-LM3-063   |
| Sine filter   |  |   |  |
| 150 % overload (CT/I <sub>H</sub> , at 50 °C)                                 |  |   | DX-SIN3-048  |
| 110 % overload (VT/I <sub>L</sub> , at 40 °C)                                 |  |   | DX-SIN3-061  |
| All-pole sine filter  |  |   |  |
| 150 % overload (CT/I <sub>H</sub> , at 50 °C)                                 |  |   | DX-SIN3-046-A  |

### Design verification as per IEC/EN 61439

|  |                   |    |   |
|--|-------------------|----|---|
| Technical data for design verification                                     |                   |    |   |
| Rated operational current for specified heat dissipation                   | I <sub>n</sub>    | A  | 46  |
| Heat dissipation per pole, current-dependent                               | P <sub>vid</sub>  | W  | 0   |
| Equipment heat dissipation, current-dependent                              | P <sub>vid</sub>  | W  | 818   |
| Static heat dissipation, non-current-dependent                             | P <sub>vs</sub>   | W  | 24.12   |
| Heat dissipation capacity  | P <sub>diss</sub> | W  | 0   |
| Operating ambient temperature min.   |                   | °C | -30   |
| Operating ambient temperature max.   |                   | °C | 60  |
|  |                   |    | Operation (with 150 % overload), allow for derating |
| IEC/EN 61439 design verification   |                   |    |   |
| 10.2 Strength of materials and parts                                       |                   |    |   |
| 10.2.2 Corrosion resistance  |                   |    | Meets the product standard's requirements.          |
| 10.2.3.1 Verification of thermal stability of enclosures                   |                   |    | Meets the product standard's requirements.          |
| 10.2.3.2 Verification of resistance of insulating materials to normal heat |                   |    | Meets the product standard's requirements.          |

|  |  |  |
|--|--|--|
| 10.2.3.3 Verification of resistance of insulating materials to abnormal heat and fire due to internal electric effects |  | Meets the product standard's requirements.   |
| 10.2.4 Resistance to ultra-violet (UV) radiation   |  | Meets the product standard's requirements.   |
| 10.2.5 Lifting   |  | Does not apply, since the entire switchgear needs to be evaluated.   |
| 10.2.6 Mechanical impact   |  | Does not apply, since the entire switchgear needs to be evaluated.   |
| 10.2.7 Inscriptions  |  | Meets the product standard's requirements.   |
| 10.3 Degree of protection of ASSEMBLIES  |  | Does not apply, since the entire switchgear needs to be evaluated.   |
| 10.4 Clearances and creepage distances   |  | Meets the product standard's requirements.   |
| 10.5 Protection against electric shock   |  | Does not apply, since the entire switchgear needs to be evaluated.   |
| 10.6 Incorporation of switching devices and components   |  | Does not apply, since the entire switchgear needs to be evaluated.   |
| 10.7 Internal electrical circuits and connections  |  | Is the panel builder's responsibility.   |
| 10.8 Connections for external conductors   |  | Is the panel builder's responsibility.   |
| 10.9 Insulation properties   |  |  |
| 10.9.2 Power-frequency electric strength   |  | Is the panel builder's responsibility.   |
| 10.9.3 Impulse withstand voltage   |  | Is the panel builder's responsibility.   |
| 10.9.4 Testing of enclosures made of insulating material   |  | Is the panel builder's responsibility.   |
| 10.10 Temperature rise   |  | The panel builder is responsible for the temperature rise calculation. Eaton will provide heat dissipation data for the devices. |
| 10.11 Short-circuit rating   |  | Is the panel builder's responsibility. The specifications for the switchgear must be observed.                                   |
| 10.12 Electromagnetic compatibility  |  | Is the panel builder's responsibility. The specifications for the switchgear must be observed.                                   |
| 10.13 Mechanical function  |  | The device meets the requirements, provided the information in the instruction leaflet (IL) is observed.                         |

## Technical data ETIM 7.0

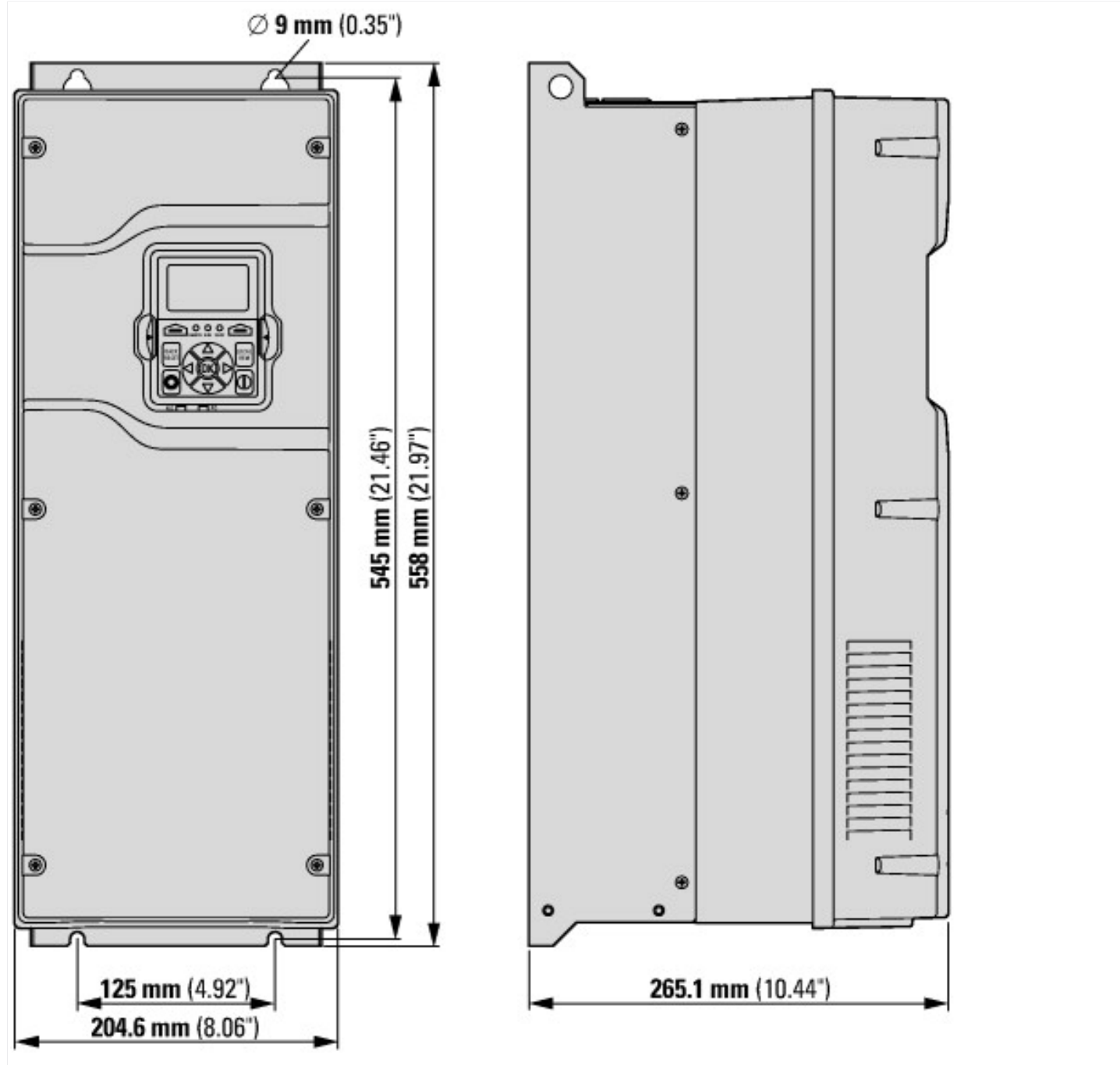
|  |    |  |           |
|--|----|--|-----------|
| Low-voltage industrial components (EG000017) / Frequency converter =< 1 kV (EC001857)  |    |  |           |
| Electric engineering, automation, process control engineering / Electrical drive / Static frequency converter / Static frequency converter = < 1 kV (ecl@ss10.0.1-27-02-31-01 [AKE177014]) |    |  |           |
| Mains voltage  | V  |  | 380 - 480 |
| Mains frequency  |    |  | 50/60 Hz  |
| Number of phases input   |    |  | 3         |
| Number of phases output  |    |  | 3         |
| Max. output frequency  | Hz |  | 400       |
| Max. output voltage  | V  |  | 480       |
| Nominal output current I <sub>2N</sub>   | A  |  | 61        |
| Max. output at quadratic load at rated output voltage  | kW |  | 30        |
| Max. output at linear load at rated output voltage   | kW |  | 44        |
| Relative symmetric net frequency tolerance   | %  |  | 10        |
| Relative symmetric net voltage tolerance   | %  |  | 10        |
| Number of analogue outputs   |    |  | 2         |
| Number of analogue inputs  |    |  | 2         |
| Number of digital outputs  |    |  | 1         |
| Number of digital inputs   |    |  | 8         |
| With control unit  |    |  | Yes       |
| Application in industrial area permitted   |    |  | Yes       |
| Application in domestic- and commercial area permitted   |    |  | Yes       |
| Supporting protocol for TCP/IP   |    |  | Yes       |
| Supporting protocol for PROFIBUS   |    |  | Yes       |
| Supporting protocol for CAN  |    |  | Yes       |
| Supporting protocol for INTERBUS   |    |  | No        |
| Supporting protocol for ASI  |    |  | No        |
| Supporting protocol for KNX  |    |  | No        |
| Supporting protocol for MODBUS   |    |  | Yes       |
| Supporting protocol for Data-Highway   |    |  | No        |
| Supporting protocol for DeviceNet  |    |  | Yes       |
| Supporting protocol for SUCONET  |    |  | No        |
| Supporting protocol for LON  |    |  | No        |

|   |  |    |             |
|---|--|----|-------------|
| Supporting protocol for PROFINET IO                 |  |    | Yes         |
| Supporting protocol for PROFINET CBA                |  |    | No          |
| Supporting protocol for SERCOS                      |  |    | No          |
| Supporting protocol for Foundation Fieldbus         |  |    | No          |
| Supporting protocol for EtherNet/IP                 |  |    | No          |
| Supporting protocol for AS-Interface Safety at Work |  |    | No          |
| Supporting protocol for DeviceNet Safety            |  |    | No          |
| Supporting protocol for INTERBUS-Safety             |  |    | No          |
| Supporting protocol for PROFIsafe                   |  |    | No          |
| Supporting protocol for SafetyBUS p                 |  |    | No          |
| Supporting protocol for BACnet                      |  |    | Yes         |
| Supporting protocol for other bus systems           |  |    | Yes         |
| Number of HW-interfaces industrial Ethernet         |  |    | 1           |
| Number of interfaces PROFINET                       |  |    | 0           |
| Number of HW-interfaces RS-232                      |  |    | 0           |
| Number of HW-interfaces RS-422                      |  |    | 0           |
| Number of HW-interfaces RS-485                      |  |    | 1           |
| Number of HW-interfaces serial TTY                  |  |    | 0           |
| Number of HW-interfaces USB                         |  |    | 0           |
| Number of HW-interfaces parallel                    |  |    | 0           |
| Number of HW-interfaces other                       |  |    | 1           |
| With optical interface                              |  |    | No          |
| With PC connection                                  |  |    | Yes         |
| Integrated breaking resistance                      |  |    | Yes         |
| 4-quadrant operation possible                       |  |    | Yes         |
| Type of converter                                   |  |    | U converter |
| Degree of protection (IP)                           |  |    | IP21        |
| Degree of protection (NEMA)                         |  |    | 1           |
| Height  |  | mm | 558         |
| Width   |  | mm | 200         |
| Depth   |  | mm | 252         |

## Approvals

|                             |  |  |  |
|-----------------------------|--|--|--|
| Product Standards           |  |  | UL508C, CSA-C22.2 No. 274-13; IEC/EN61800-3; IEC/EN61800-5; CE marking |
| UL File No.                 |  |  | E134360  |
| UL Category Control No.     |  |  | NMMS, NMMS7  |
| CSA File No.                |  |  | UL report applies to both US and Canada                                |
| North America Certification |  |  | UL listed, certified by UL for use in Canada                           |
| Suitable for                |  |  | Branch circuits  |
| Max. Voltage Rating         |  |  | 3-500 V AC IEC: TN-S UL/CSA: 'Y' (Solidly Grounded Wey)                |
| Degree of Protection        |  |  | IP21/NEMA1   |

## Dimensions



## Additional product information (links)

|               |   |
|---------------|---|
| Documentation | <a href="http://www.eaton.eu/Europe/Electrical/ProductsServices/AutomationControl/SwitchingProtectingDrivingMotors/PowerXLfrequencydrives/DG1GeneralPurposeDrives/index.htm?wtredirect=www.eaton.eu/dg1#tabs-7">http://www.eaton.eu/Europe/Electrical/ProductsServices/AutomationControl/SwitchingProtectingDrivingMotors/PowerXLfrequencydrives/DG1GeneralPurposeDrives/index.htm?wtredirect=www.eaton.eu/dg1#tabs-7</a> |
| Manuals       | <a href="http://www.eaton.eu/Europe/Electrical/ProductsServices/AutomationControl/SwitchingProtectingDrivingMotors/PowerXLfrequencydrives/DG1GeneralPurposeDrives/index.htm?wtredirect=www.eaton.eu/dg1#tabs-8">http://www.eaton.eu/Europe/Electrical/ProductsServices/AutomationControl/SwitchingProtectingDrivingMotors/PowerXLfrequencydrives/DG1GeneralPurposeDrives/index.htm?wtredirect=www.eaton.eu/dg1#tabs-8</a> |



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## Delivery program

|                                    |                 |    |   |
|------------------------------------|-----------------|----|---|
| Product range                      |                 |    | Variable frequency drives   |
| Part group reference (e.g. DIL)    |                 |    | DG1   |
| Rated operational voltage          | U <sub>e</sub>  |    | 400 V AC, 3-phase<br>480 V AC, 3-phase<br>500 V AC, 3-phase   |
| Output voltage with V <sub>e</sub> | U <sub>2</sub>  |    | 400 V AC, 3-phase<br>480 V AC, 3-phase<br>500 V AC, 3-phase   |
| Mains voltage (50/60Hz)            | U <sub>LN</sub> | V  | 380 (-15%) - 500 (+10%)   |
| <b>Rated operational current</b>   |                 |    |   |
| At 150% overload                   | I <sub>e</sub>  | A  | 46  |
| At 110% overload                   | I <sub>e</sub>  | A  | 61  |
| Note                               |                 |    | Rated operational current for a switching frequency of 1 - 12 kHz and an ambient temperature of +50 °C for a 150% overload and +40 °C for a 110% overload       |
| <b>Assigned motor rating</b>       |                 |    |   |
| Note                               |                 |    | for normal internally and externally ventilated 4 pole, three-phase asynchronous motors with 1500 rpm <sup>-1</sup> at 50 Hz or 1800 min <sup>-1</sup> at 60 Hz |
| Note                               |                 |    | Overload cycle for 60 s every 600 s   |
| Note                               |                 |    | at 400 V, 50 Hz   |
| 150 % Overload                     | P               | kW | 22  |
| 110 % Overload                     | P               | kW | 30  |
| 150 % Overload                     | I <sub>M</sub>  | A  | 41  |
| 110 % Overload                     | I <sub>M</sub>  | A  | 55.2  |
| Note                               |                 |    | at 500 V, 50 Hz   |
| 150 % Overload                     | P               | kW | 30  |
| 110 % Overload                     | P               | kW | 37  |
| 150 % Overload                     | I <sub>M</sub>  | A  | 44  |
| 110 % Overload                     | I <sub>M</sub>  | A  | 54  |
| Note                               |                 |    | at 480 V, 60 Hz   |
| 150 % Overload                     | P               | HP | 30  |
| 110 % Overload                     | P               | HP | 40  |
| 150 % Overload                     | I <sub>M</sub>  | A  | 40  |
| 110 % Overload                     | I <sub>M</sub>  | A  | 52  |
| Degree of Protection               |                 |    | IP21/NEMA1  |
| Interface/field bus (built-in)     |                 |    | Modbus RTU<br>Modbus TCP<br>BACnet MS/TP<br>Ethernet IP   |
| Fieldbus connection (optional)     |                 |    | PROFIBUS<br>CANopen®<br>DeviceNet<br>SmartWire-DT   |
| Fitted with                        |                 |    | Radio interference suppression filter<br>Additional PCB protection<br>Multi-line graphic display<br>Brake chopper<br>DC link choke                              |



|                            |  |  |  |
|----------------------------|--|--|--|
| Frame size                 |  |  | FS3  |
| Connection to SmartWire-DT |  |  | yes<br>in conjunction with DXG-NET-SWD SmartWire DT module |

## Technical data

### General

|                                   |          |    |  |
|-----------------------------------|----------|----|--|
| Standards                         |          |    | Specification for general requirements: IEC/EN 61800-2<br>EMC requirements: IEC/EN 61800-3<br>Safety requirements: IEC/EN 61800-5  |
| Certifications                    |          |    | CE, UL, cUL, c-Tick, UkrSEPRO, EAC   |
| Production quality                |          |    | RoHS, ISO 9001   |
| Climatic proofing                 | $\rho_w$ | %  | < 95%, average relative humidity (RH), non-condensing, non-corrosive   |
| Air quality                       |          |    | 3C2, 3S2   |
| Ambient temperature               |          |    |  |
| operation (150 % overload)        | $\theta$ | °C | -30 - +50 (max. +60 with 1 % derating per Kelvin temperature rise)   |
| operation (110 % overload)        | $\theta$ | °C | -30 - +40 (max. +55 mit 1 % Derating pro Kelvin Temperaturerhöhung)  |
| Storage                           | $\theta$ | °C | -40 - +70  |
| Overvoltage category              |          |    | III  |
| Pollution degree                  |          |    | 2  |
| Radio interference level          |          |    |  |
| Radio interference class (EMC)    |          |    | C1 (with external filter, for conducted emissions only), C2, C3, depending on the motor cable length, the connected load, and ambient conditions. External radio interference suppression filters (optional) may be necessary. |
| Environment (EMC)                 |          |    | 1st and 2nd environments as per EN 61800-3   |
| maximum motor cable length        | l        | m  | C2 ≤ 10 m<br>C3 ≤ 50 m   |
| Mechanical shock resistance       |          | g  | EN 61800-5-1, EN 60068-2-27<br>UPS drop test (for weights inside the UPS frame)<br>Storage and transportation: maximum 15 g, 11 ms (inside the packaging)  |
| Vibration                         |          |    | EN 61800-5-1, EN 60068-2-6: 5 - 150 Hz<br>Amplitude: 1 mm (peak) at 5 - 15.8 Hz<br>Maximum acceleration amplitude: 1 g at 15.8 – 150 Hz  |
| Mounting position                 |          |    | Vertical   |
| Altitude                          |          | m  | 0 - 1000 m above sea level<br>Above 1000 m: 1% derating for every 100 m<br>max. 3000 m (2000 m for Corner Grounded TN Systems)   |
| Degree of Protection              |          |    | IP21/NEMA1   |
| Protection against direct contact |          |    | BGV A3 (VBG4, finger- and back-of-hand proof)  |

### Main circuit

|   |          |    |   |
|---|----------|----|---|
| Supply                                  |          |    |   |
| Rated operational voltage               | $U_e$    |    | 400 V AC, 3-phase<br>480 V AC, 3-phase<br>500 V AC, 3-phase                     |
| Mains voltage (50/60Hz)                 | $U_{LN}$ | V  | 380 (-15%) - 500 (+10%)   |
| Input current (150% overload)           | $I_{LN}$ | A  | 42.6  |
| Input current (110% overload)           | $I_{LN}$ | T  | 55.7  |
| System configuration                    |          |    | TN-S, TN-C, TN-C-S, TT, IT  |
| Supply frequency                        | $f_{LN}$ | Hz | 50/60   |
| Frequency range                         | $f_{LN}$ | Hz | 45 - 66   |
| Mains switch-on frequency               |          |    | Maximum of one time every 60 seconds  |
| Mains current distortion                | THD      | %  | 32.6  |
| Rated conditional short-circuit current | $I_q$    | kA | < 100   |
| Power section                           |          |    |   |
| Function                                |          |    | Variable frequency drive with internal DC link, DC link choke and IGBT inverter |
| Overload current (150% overload)        | $I_L$    | A  | 69  |
| Overload current (110% overload)        | $I_L$    | A  | 67.1  |
| max. starting current (High Overload)   | $I_H$    | %  | 200   |
| Note about max. starting current        |          |    | for 2 seconds every 20 seconds  |
| Output voltage with $V_e$               | $U_2$    |    | 400 V AC, 3-phase<br>480 V AC, 3-phase<br>500 V AC, 3-phase                     |

|   |            |          |   |
|---|------------|----------|---|
| Output Frequency  | $f_2$      | Hz       | 0 - 50/60 (max. 400)  |
| Switching frequency   | $f_{PWM}$  | kHz      | 4<br>adjustable 1 - 12  |
| Operation Mode  |            |          | U/f control<br>Speed control with slip compensation<br>sensorless vector control (SLV)<br>Torque regulation   |
| Frequency resolution (setpoint value)                       | $\Delta f$ | Hz       | 0.01  |
| Rated operational current                                   |            |          |   |
| At 150% overload  | $I_e$      | A        | 46  |
| At 110% overload  | $I_e$      | A        | 61  |
| Note  |            |          | Rated operational current for a switching frequency of 1 - 12 kHz and an ambient temperature of +50 °C for a 150% overload and +40 °C for a 110% overload         |
| Motor current limit   | $I$        | A        | $0.1 - 2 \times I_H$ (CT)   |
| Power loss  |            |          |   |
| Heat dissipation at rated operational current $I_e = 150\%$ | $P_V$      | W        | 541   |
| Heat dissipation at rated operational current $I_e = 110\%$ | $P_V$      | W        | 818   |
| Efficiency  | $\eta$     | %        | 97.7  |
| Maximum leakage current to ground (PE) without motor        | $I_{PE}$   | mA       | 12.2  |
| Fan   |            |          | temperature controlled<br>Tool-less swapping  |
| Internal fan delivery rate                                  |            | $m^3/h$  | 144   |
| Fitted with   |            |          | Radio interference suppression filter<br>Additional PCB protection<br>Multi-line graphic display<br>Brake chopper<br>DC link choke                                |
| Safety function   |            |          | STO (Safe Torque Off, SIL1, PLc Cat 1)  |
| Frame size  |            |          | FS3   |
| Motor feeder  |            |          |   |
| Note  |            |          | for normal internally and externally ventilated 4 pole, three-phase asynchronous motors with $1500 \text{ rpm}^{-1}$ at 50 Hz or $1800 \text{ min}^{-1}$ at 60 Hz |
| Note  |            |          | Overload cycle for 60 s every 600 s   |
| Note  |            |          | at 400 V, 50 Hz   |
| 150 % Overload  | P          | kW       | 22  |
| 110 % Overload  | P          | kW       | 30  |
| Note  |            |          | at 500 V, 50 Hz   |
| 150 % Overload  | P          | kW       | 30  |
| 110 % Overload  | P          | kW       | 37  |
| Note  |            |          | at 480 V, 60 Hz   |
| 150 % Overload  | P          | HP       | 30  |
| 110 % Overload  | P          | HP       | 40  |
| maximum permissible cable length                            | $l$        | m        | screened: 150   |
| Apparent power  |            |          |   |
| Apparent power at rated operation 400 V                     | S          | kVA      | 42.3  |
| Apparent power at rated operation 480 V                     | S          | kVA      | 52.8  |
| Braking function  |            |          |   |
| Standard braking torque                                     |            |          | max. 30 % $M_N$   |
| DC braking torque   |            |          | adjustable to 150 %   |
| Braking torque with external braking resistance             |            |          | Max. 100% of rated operational current $I_e$ with external braking resistor   |
| minimum external braking resistance                         | $R_{min}$  | $\Omega$ | 14  |
| Switch-on threshold for the braking transistor              | $U_{DC}$   | V        | 850 V DC  |
| DC braking  | %          | $I/I_e$  | $\leq 150$ , adjustable   |
| <b>Control section</b>                                      |            |          |   |
| External control voltage                                    | $U_c$      | V        | 24 V DC (max. 250 mA options incl.)   |
| Reference voltage   | $U_s$      | V        | 10 V DC (max. 10 mA)  |
| Analog inputs   |            |          | 2, parameterizable, 0 - 10 V DC, 2 - 10 V DC, -10 - +10 V DC, 0/4 - 20 mA   |
| Analog outputs  |            |          | 2, parameterizable, 0 - 10 V, 0/4 - 20 mA   |
| Digital inputs  |            |          | 8, parameterizable, max. 30 V DC  |

|                                |  |  |   |
|--------------------------------|--|--|---|
| Digital outputs                |  |  | 1, parameterizable, 24 V DC   |
| Relay outputs                  |  |  | 3, parameterizable, 2 changeover contacts and 1 N/O, 6 A (240 VAC) / 6 A (24 VDC) |
| Interface/field bus (built-in) |  |  | Modbus RTU<br>Modbus TCP<br>BACnet MS/TP<br>Ethernet IP                           |
| Expansion slots                |  |  | 2   |

### Assigned switching and protective elements

|   |  |   |  |
|---|--|---|--|
| Power Wiring  |  |   |  |
| Safety device (fuse or miniature circuit-breaker)                             |  |   |  |
| IEC (Type B, gG), 150 %   |  |   | PKZM4-50   |
| IEC (Type B, gG), 110 %   |  |   | PKZM4-63   |
| UL (Class CC or J)  |  | A | 80   |
| Mains contactor   |  |   |  |
| 150 % overload (CT/I <sub>H</sub> , at 50 °C)                                 |  |   | DILM40   |
| 110 % overload (VT/I <sub>L</sub> , at 40 °C)                                 |  |   | DILM50   |
| Main choke  |  |   |  |
| 150 % overload (CT/I <sub>H</sub> , at 50 °C)                                 |  |   | Integrated DC link choke, uk = 5%  |
| 110 % overload (VT/I <sub>L</sub> , at 40 °C)                                 |  |   | Integrated DC link choke, uk = 5%  |
| Radio interference suppression filter (external, 150 %)                       |  |   | DX-EMC34-055   |
| Radio interference suppression filter (external, 110 %)                       |  |   | DX-EMC34-075   |
| Radio interference suppression filter, low leakage currents (external, 150 %) |  |   | DX-EMC34-055-L   |
| Radio interference suppression filter, low leakage currents (external, 110 %) |  |   | DX-EMC34-075-L   |
| Note regarding radio interference suppression filter                          |  |   | Optional external radio interference suppression filter for longer motor cable lengths and for use in different EMC environments |
| DC link connection  |  |   |  |
| Braking resistance  |  |   |  |
| 10 % duty factor (DF)   |  |   | P:3 x DX-BR047-3K1   |
| 20 % duty factor (DF)   |  |   | P:3 x DX-BR047-5K1   |
| 40 % duty factor (DF)   |  |   | P:3 x DX-BR047-9K2   |
| Notes concerning braking resistances:   |  |   | P:n = "n" resistors connected in parallel  |
| Motor feeder  |  |   |  |
| motor choke   |  |   |  |
| 150 % overload (CT/I <sub>H</sub> , at 50 °C)                                 |  |   | DX-LM3-050   |
| 110 % overload (VT/I <sub>L</sub> , at 40 °C)                                 |  |   | DX-LM3-063   |
| Sine filter   |  |   |  |
| 150 % overload (CT/I <sub>H</sub> , at 50 °C)                                 |  |   | DX-SIN3-048  |
| 110 % overload (VT/I <sub>L</sub> , at 40 °C)                                 |  |   | DX-SIN3-061  |
| All-pole sine filter  |  |   |  |
| 150 % overload (CT/I <sub>H</sub> , at 50 °C)                                 |  |   | DX-SIN3-046-A  |

### Design verification as per IEC/EN 61439

|  |                   |    |   |
|--|-------------------|----|---|
| Technical data for design verification                                     |                   |    |   |
| Rated operational current for specified heat dissipation                   | I <sub>n</sub>    | A  | 46  |
| Heat dissipation per pole, current-dependent                               | P <sub>vid</sub>  | W  | 0   |
| Equipment heat dissipation, current-dependent                              | P <sub>vid</sub>  | W  | 818   |
| Static heat dissipation, non-current-dependent                             | P <sub>vs</sub>   | W  | 24.12   |
| Heat dissipation capacity  | P <sub>diss</sub> | W  | 0   |
| Operating ambient temperature min.   |                   | °C | -30   |
| Operating ambient temperature max.   |                   | °C | 60  |
|  |                   |    | Operation (with 150 % overload), allow for derating |
| IEC/EN 61439 design verification   |                   |    |   |
| 10.2 Strength of materials and parts                                       |                   |    |   |
| 10.2.2 Corrosion resistance  |                   |    | Meets the product standard's requirements.          |
| 10.2.3.1 Verification of thermal stability of enclosures                   |                   |    | Meets the product standard's requirements.          |
| 10.2.3.2 Verification of resistance of insulating materials to normal heat |                   |    | Meets the product standard's requirements.          |

|  |  |  |
|--|--|--|
| 10.2.3.3 Verification of resistance of insulating materials to abnormal heat and fire due to internal electric effects |  | Meets the product standard's requirements.   |
| 10.2.4 Resistance to ultra-violet (UV) radiation   |  | Meets the product standard's requirements.   |
| 10.2.5 Lifting   |  | Does not apply, since the entire switchgear needs to be evaluated.   |
| 10.2.6 Mechanical impact   |  | Does not apply, since the entire switchgear needs to be evaluated.   |
| 10.2.7 Inscriptions  |  | Meets the product standard's requirements.   |
| 10.3 Degree of protection of ASSEMBLIES  |  | Does not apply, since the entire switchgear needs to be evaluated.   |
| 10.4 Clearances and creepage distances   |  | Meets the product standard's requirements.   |
| 10.5 Protection against electric shock   |  | Does not apply, since the entire switchgear needs to be evaluated.   |
| 10.6 Incorporation of switching devices and components   |  | Does not apply, since the entire switchgear needs to be evaluated.   |
| 10.7 Internal electrical circuits and connections  |  | Is the panel builder's responsibility.   |
| 10.8 Connections for external conductors   |  | Is the panel builder's responsibility.   |
| 10.9 Insulation properties   |  |  |
| 10.9.2 Power-frequency electric strength   |  | Is the panel builder's responsibility.   |
| 10.9.3 Impulse withstand voltage   |  | Is the panel builder's responsibility.   |
| 10.9.4 Testing of enclosures made of insulating material   |  | Is the panel builder's responsibility.   |
| 10.10 Temperature rise   |  | The panel builder is responsible for the temperature rise calculation. Eaton will provide heat dissipation data for the devices. |
| 10.11 Short-circuit rating   |  | Is the panel builder's responsibility. The specifications for the switchgear must be observed.                                   |
| 10.12 Electromagnetic compatibility  |  | Is the panel builder's responsibility. The specifications for the switchgear must be observed.                                   |
| 10.13 Mechanical function  |  | The device meets the requirements, provided the information in the instruction leaflet (IL) is observed.                         |

## Technical data ETIM 7.0

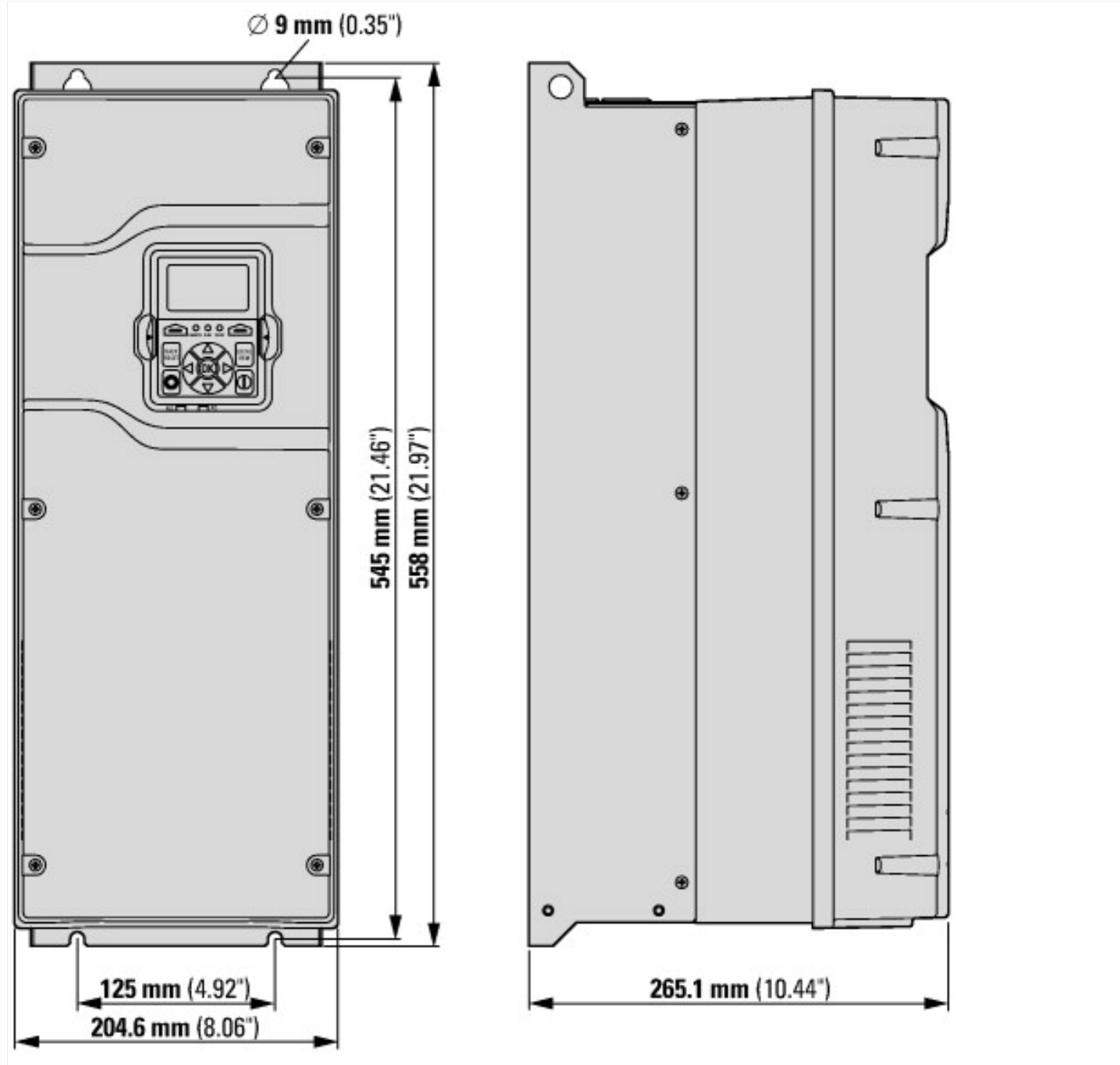
|  |    |  |           |
|--|----|--|-----------|
| Low-voltage industrial components (EG000017) / Frequency converter =< 1 kV (EC001857)  |    |  |           |
| Electric engineering, automation, process control engineering / Electrical drive / Static frequency converter / Static frequency converter = < 1 kV (ecl@ss10.0.1-27-02-31-01 [AKE177014]) |    |  |           |
| Mains voltage  | V  |  | 380 - 480 |
| Mains frequency  |    |  | 50/60 Hz  |
| Number of phases input   |    |  | 3         |
| Number of phases output  |    |  | 3         |
| Max. output frequency  | Hz |  | 400       |
| Max. output voltage  | V  |  | 480       |
| Nominal output current I <sub>2N</sub>   | A  |  | 61        |
| Max. output at quadratic load at rated output voltage  | kW |  | 30        |
| Max. output at linear load at rated output voltage   | kW |  | 44        |
| Relative symmetric net frequency tolerance   | %  |  | 10        |
| Relative symmetric net voltage tolerance   | %  |  | 10        |
| Number of analogue outputs   |    |  | 2         |
| Number of analogue inputs  |    |  | 2         |
| Number of digital outputs  |    |  | 1         |
| Number of digital inputs   |    |  | 8         |
| With control unit  |    |  | Yes       |
| Application in industrial area permitted   |    |  | Yes       |
| Application in domestic- and commercial area permitted   |    |  | Yes       |
| Supporting protocol for TCP/IP   |    |  | Yes       |
| Supporting protocol for PROFIBUS   |    |  | Yes       |
| Supporting protocol for CAN  |    |  | Yes       |
| Supporting protocol for INTERBUS   |    |  | No        |
| Supporting protocol for ASI  |    |  | No        |
| Supporting protocol for KNX  |    |  | No        |
| Supporting protocol for MODBUS   |    |  | Yes       |
| Supporting protocol for Data-Highway   |    |  | No        |
| Supporting protocol for DeviceNet  |    |  | Yes       |
| Supporting protocol for SUCONET  |    |  | No        |
| Supporting protocol for LON  |    |  | No        |

|   |  |    |             |
|---|--|----|-------------|
| Supporting protocol for PROFINET IO                 |  |    | Yes         |
| Supporting protocol for PROFINET CBA                |  |    | No          |
| Supporting protocol for SERCOS                      |  |    | No          |
| Supporting protocol for Foundation Fieldbus         |  |    | No          |
| Supporting protocol for EtherNet/IP                 |  |    | No          |
| Supporting protocol for AS-Interface Safety at Work |  |    | No          |
| Supporting protocol for DeviceNet Safety            |  |    | No          |
| Supporting protocol for INTERBUS-Safety             |  |    | No          |
| Supporting protocol for PROFIsafe                   |  |    | No          |
| Supporting protocol for SafetyBUS p                 |  |    | No          |
| Supporting protocol for BACnet                      |  |    | Yes         |
| Supporting protocol for other bus systems           |  |    | Yes         |
| Number of HW-interfaces industrial Ethernet         |  |    | 1           |
| Number of interfaces PROFINET                       |  |    | 0           |
| Number of HW-interfaces RS-232                      |  |    | 0           |
| Number of HW-interfaces RS-422                      |  |    | 0           |
| Number of HW-interfaces RS-485                      |  |    | 1           |
| Number of HW-interfaces serial TTY                  |  |    | 0           |
| Number of HW-interfaces USB                         |  |    | 0           |
| Number of HW-interfaces parallel                    |  |    | 0           |
| Number of HW-interfaces other                       |  |    | 1           |
| With optical interface                              |  |    | No          |
| With PC connection                                  |  |    | Yes         |
| Integrated breaking resistance                      |  |    | Yes         |
| 4-quadrant operation possible                       |  |    | Yes         |
| Type of converter                                   |  |    | U converter |
| Degree of protection (IP)                           |  |    | IP21        |
| Degree of protection (NEMA)                         |  |    | 1           |
| Height  |  | mm | 558         |
| Width   |  | mm | 200         |
| Depth   |  | mm | 252         |

## Approvals

|                             |  |  |  |
|-----------------------------|--|--|--|
| Product Standards           |  |  | UL508C, CSA-C22.2 No. 274-13; IEC/EN61800-3; IEC/EN61800-5; CE marking |
| UL File No.                 |  |  | E134360  |
| UL Category Control No.     |  |  | NMMS, NMMS7  |
| CSA File No.                |  |  | UL report applies to both US and Canada                                |
| North America Certification |  |  | UL listed, certified by UL for use in Canada                           |
| Suitable for                |  |  | Branch circuits  |
| Max. Voltage Rating         |  |  | 3-500 V AC IEC: TN-S UL/CSA: 'Y' (Solidly Grounded Wey)                |
| Degree of Protection        |  |  | IP21/NEMA1   |

## Dimensions



## Additional product information (links)

|               |   |
|---------------|---|
| Documentation | <a href="http://www.eaton.eu/Europe/Electrical/ProductsServices/AutomationControl/SwitchingProtectingDrivingMotors/PowerXLfrequencydrives/DG1GeneralPurposeDrives/index.htm?wtredirect=www.eaton.eu/dg1#tabs-7">http://www.eaton.eu/Europe/Electrical/ProductsServices/AutomationControl/SwitchingProtectingDrivingMotors/PowerXLfrequencydrives/DG1GeneralPurposeDrives/index.htm?wtredirect=www.eaton.eu/dg1#tabs-7</a> |
| Manuals       | <a href="http://www.eaton.eu/Europe/Electrical/ProductsServices/AutomationControl/SwitchingProtectingDrivingMotors/PowerXLfrequencydrives/DG1GeneralPurposeDrives/index.htm?wtredirect=www.eaton.eu/dg1#tabs-8">http://www.eaton.eu/Europe/Electrical/ProductsServices/AutomationControl/SwitchingProtectingDrivingMotors/PowerXLfrequencydrives/DG1GeneralPurposeDrives/index.htm?wtredirect=www.eaton.eu/dg1#tabs-8</a> |